

Reactive Turing Machines and ACP_{τ}

Paul van Tilburg

(joint work with Jos Baeten and Bas Luttik)

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TU / **e**

Technische Universiteit
Eindhoven
University of Technology

Where innovation starts

- ▶ Historical context
- ▶ Motivation
- ▶ Reactive Turing machine
- ▶ Results
- ▶ Related & future work

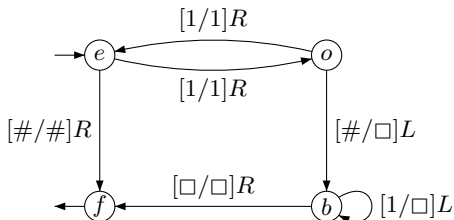
A(utomatic)-machines (later: Turing machines)

- ▶ Defined by Alan Turing in 1936
- ▶ Infinite memory in the form of a tape
- ▶ Head that reads/writes one symbol at a time
- ▶ Finite control of the head
 - reading and writing
 - moving



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$\mathcal{M} = (\mathcal{S}, \mathcal{D}, \rightarrow, \uparrow, \downarrow)$ with

$\mathcal{S} = \{e, o, f, b\}$

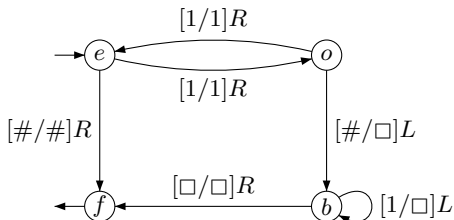
$\mathcal{D} = \{1, \#\}$

$\uparrow = e$

$\downarrow = \{f\}$

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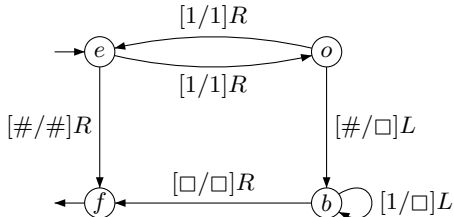
Input: $\dots \bar{1}111\#\dots$



Output: $\dots 1111\#\bar{\square}\dots$

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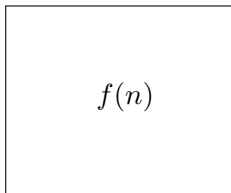


Input: $\dots \bar{1} 1 1 \# \dots$

Output: $\dots \bar{\square} \dots$

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↓
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Universal Turing machines

- ▶ Church-Turing thesis:
“Everything computable is computable by a Turing machine”
- ▶ Models a computation/function
 - The TM converts input on the tape to output
- ▶ Model is also close to a computer of the '70s (program, CPU, RAM)
 - Input available at the start
 - Calculation is performed
 - Output generated at the end
- ▶ Criticism possible on suitability as a theoretical model of a modern-day computer
- ▶ Still, the TM entered the books as theoretical model
- ▶ (However, still works well for models of computations!)

“A Turing machine cannot fly a plane, but a real computer can!”

Properties

- ▶ Non-termination
- ▶ Interaction (with the environment)

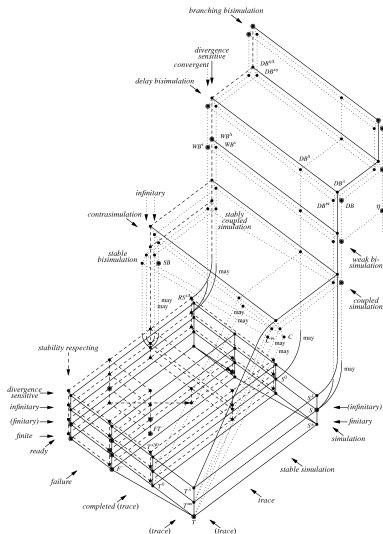
Examples

- ▶ Cloud computing
- ▶ Mobile phones
- ▶ ...
- ▶ Processes of an operating system
- ▶ Objects in a virtual machine

- ▶ Started with Petrinets in the '60s
- ▶ Given boost by Milner in the '70s
- ▶ Goals for concurrency theory according to Milner:
 - Study concurrency and **interaction** in isolation
 - Only a **single** combiner for combining processes
- ▶ This work is done within the MoCAP project
 - Consider definitions and results from automata theory
 - ... using a process-theoretic point of view
 - Obtain stronger results using concurrency theory
 - For example by considering (branching) bisimulation
- ▶ Side-goal: the design and teaching of a new course
 - In a theoretical course the model could prove useful

Linear time—branching time spectrum

- ▶ By Van Glabbeek in 1993
- ▶ Spectrum gives us many equivalences
- ▶ Goal: be as high in the spectrum as possible
- ▶ Branching bisimulation

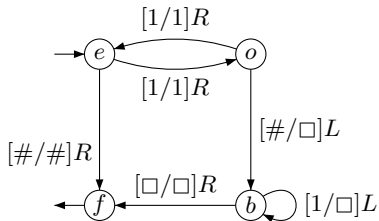


To summarise

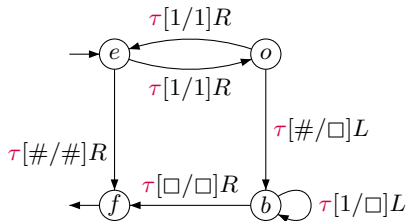
- ▶ We want a **conceptual model of a computer** rather than a model of computation
- ▶ We want to have non-termination and to make **interaction explicit**
- ▶ We use **concurrency theory** to have a plethora of process calculi, behavioural equivalences at our disposal
- ▶ Finite control is a program running on the CPU, tape is memory, interaction possible via network or I/O to user

- ▶ We aim to **integrate** computability and concurrency theory
- ▶ Our aim is not to increase the computational power of the traditional model nor to investigate the extra expressivity of interaction

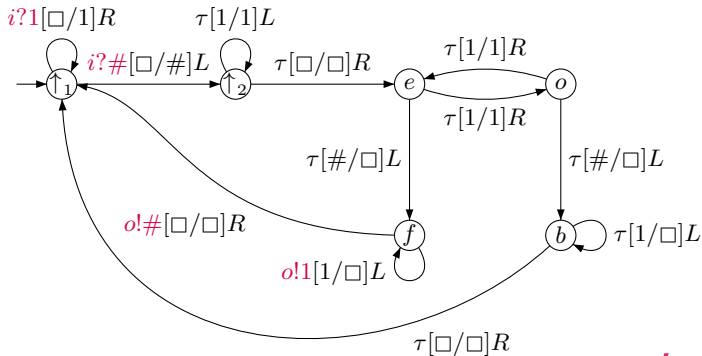
Let's consider an example:

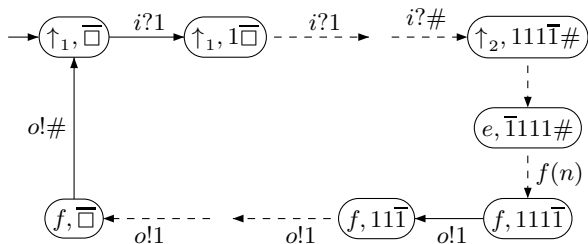


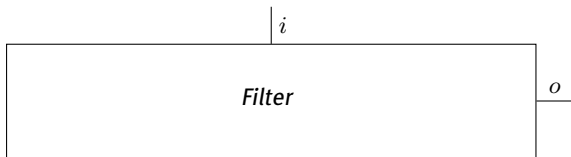
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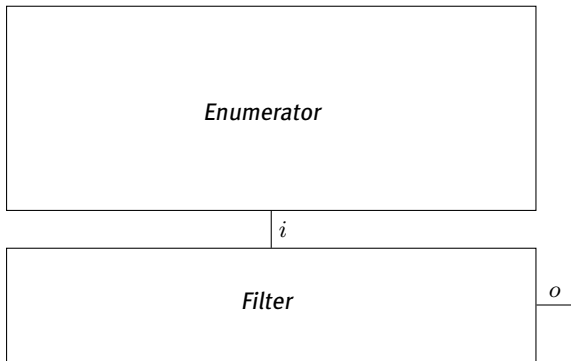


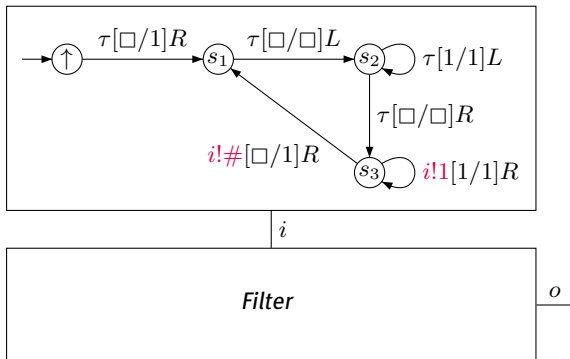
Let's consider an example:

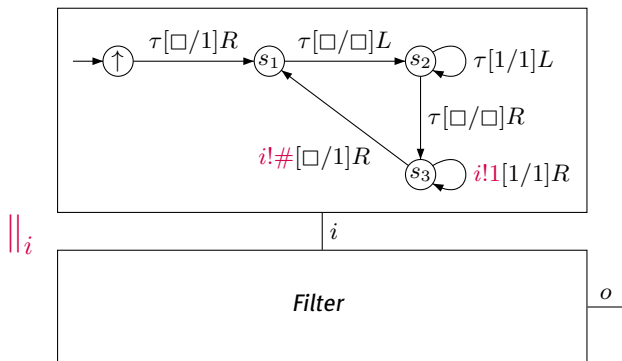


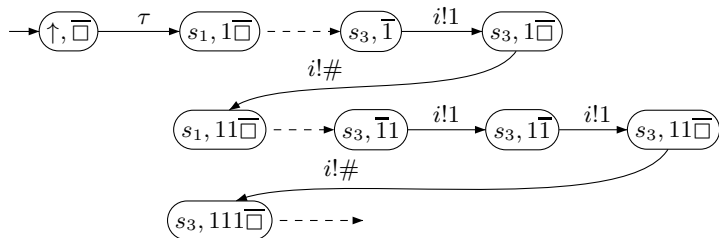


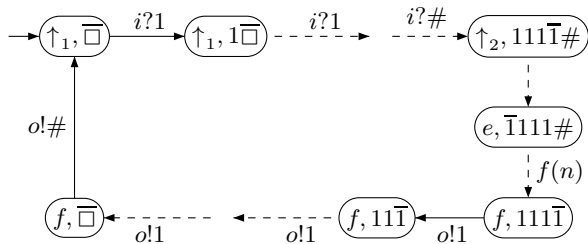
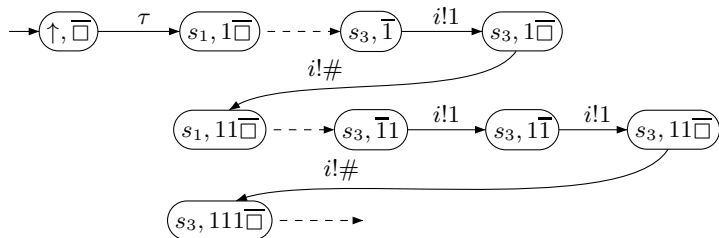


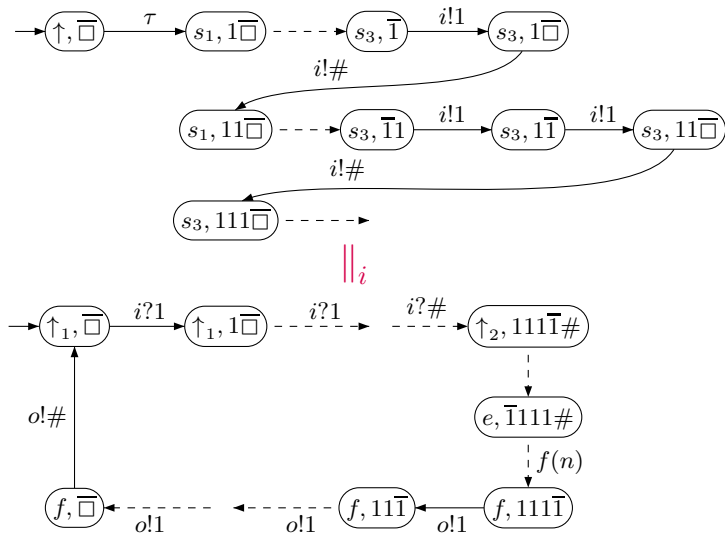


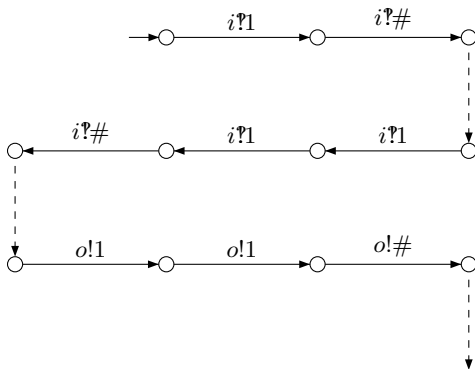


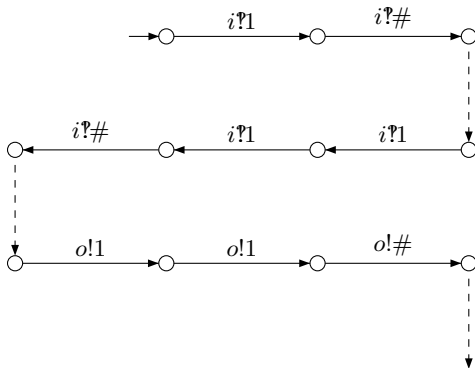












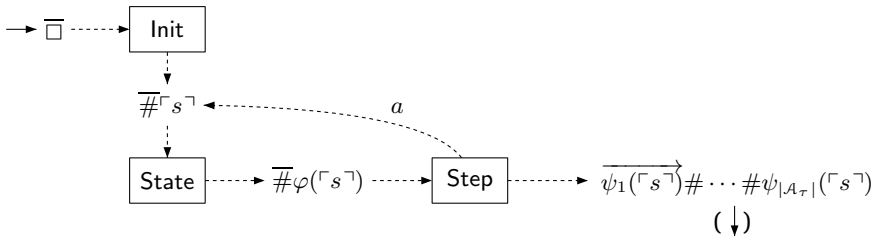
- ▶ The examples are deterministic RTM for simplification purposes

Expressivity

1. Effective transition systems are branching bisimilar with transition systems associated with with an RTM

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Notes

- ▶ In one and only one state we have to make the choice!
- ▶ In case of bounded computable transition systems we can be divergence-sensitive!

Corollary

Parallelism does not add computational power

Expressivity

1. Effective transition systems are branching bisimilar with transition systems associated with with an RTM
2. Deterministic computable transition systems are branching bisimilar with transition systems associated with with an RTM
3. For every RTM there exists a finite recursive specification in ACP_{τ} such that the respective associated transition systems are branching bisimilar

We have established

- ▶ ... a conceptual model of a computer
- ▶ ... that integrates computability and concurrency theory
- ▶ ... and implies the classical Turing machine

Related work

- ▶ Persistent Turing machines by Goldin, Smolka, Attie, Sonderegger
- ▶ Interactive Turing machines with advice by Van Leeuwen & Wiedermann
- ▶ ...

Future work

- ▶ Universal reactive Turing machine
- ▶ Variant definitions (e.g. different termination conditions)
- ▶ Relation with persistent Turing machine and interactive Turing machine with advice
- ▶ Relation with process calculi, e.g. π -calculus

Thank you!

Questions?